

Traffic Sign Detection and Recognition

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Supervisor, first examiner: Dr Jonathon S. Hare
Second examiner: Dr Adam Prügel-Bennett

Business Goal

- Video/image coupled with geo-location
- Automatic locator for traffic sign



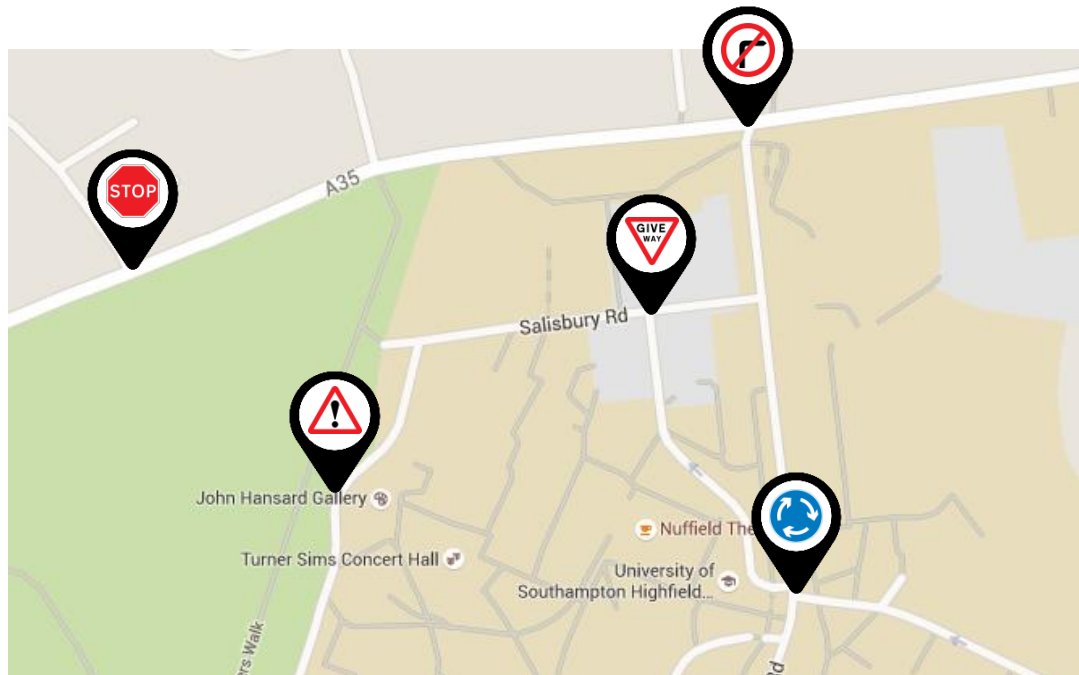
Business Goal

- Video/image coupled with geo-location
- Automatic locator for traffic sign



Business Goal

- Video/image coupled with geo-location
- Automatic locator for traffic sign
- Enrich maps with information



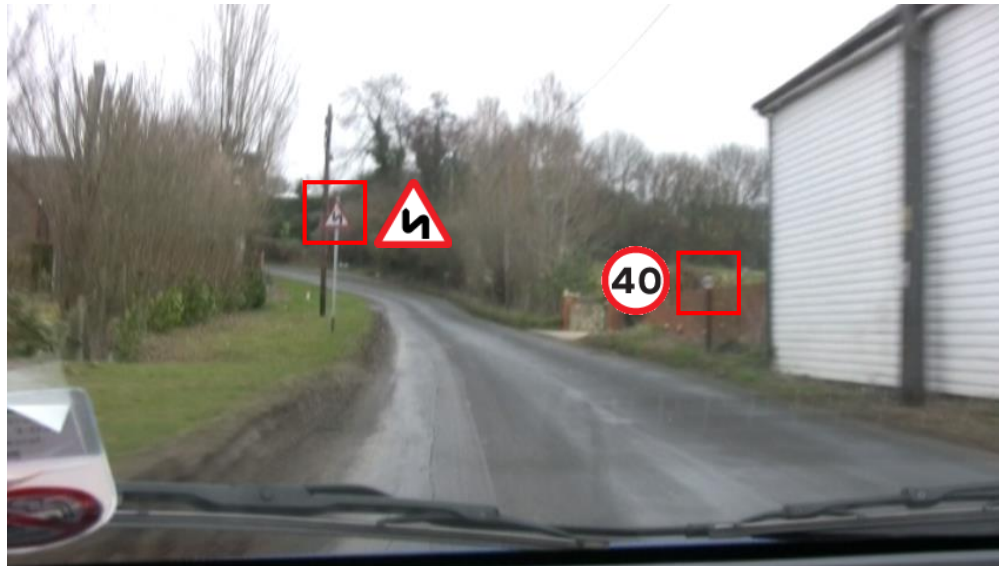
Scientific Problem

- Localisation and detection



Scientific Problem

- Localisation and detection
- Recognition



Scientific Problem

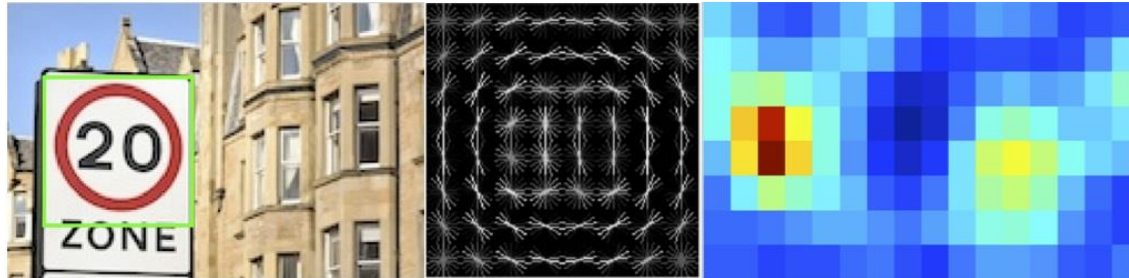
- Localisation and detection
- Recognition
- Tracking



Recognition

Recognition: Previous Work

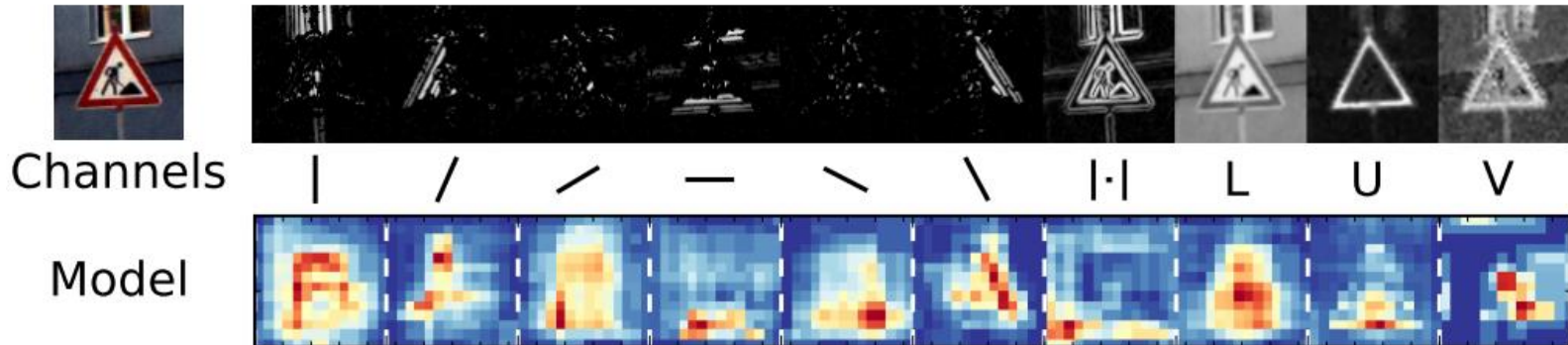
- Handcrafted feature detectors and extractors
 - Histogram of Oriented Gradients (HOG) - [Greenhalgh 2012, Zaklouta 2011]



Source: <http://www.robots.ox.ac.uk/~vgg/practicals/category-detection/index.html>

Recognition: Previous Work

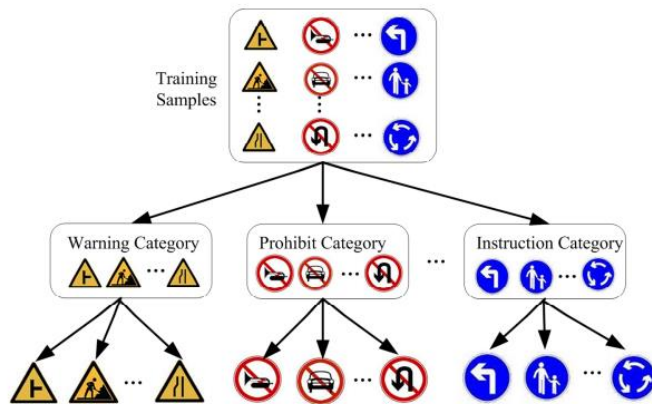
- Handcrafted feature detectors and extractors
 - Histogram of Oriented Gradients (HOG) - [Greenhalgh 2012, Zaklouta 2011]
 - Integral Channel Features (ICF) - [Mathias 2013]



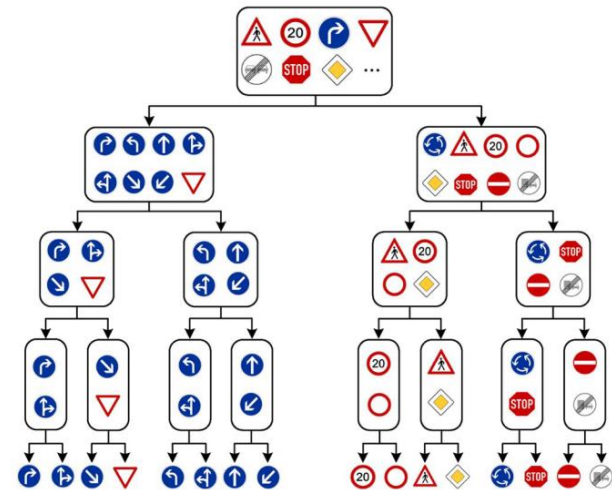
Source: [Mathias 2013]

Recognition: Previous Work

- Handcrafted feature detectors and extractors
 - Histogram of Oriented Gradients (HOG) - [Greenhalgh 2012, Zaklouta 2011]
 - Integral Channel Features (ICF) - [Mathias 2013]
 - Categories-first-assigned Tree (CTA-Tree) - [Liu 2013]
 - Split-Flow Cascade Tree (SFC-Tree) - [Liu 2014]



CTA-Tree, source: [Liu 2013]



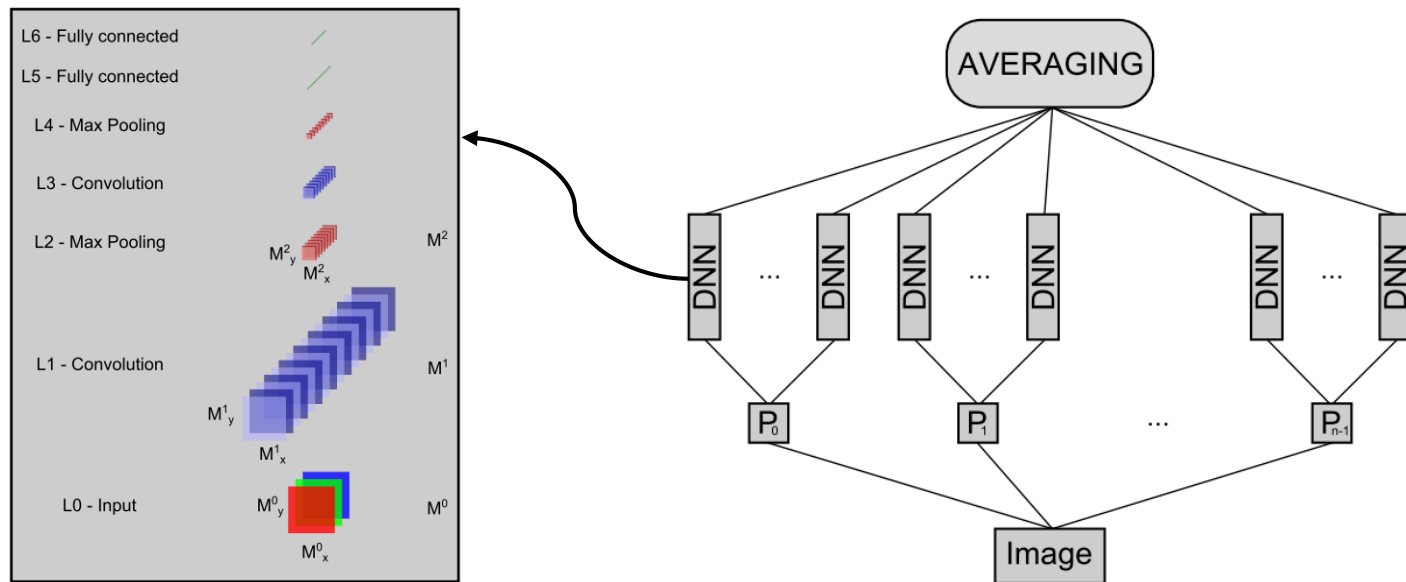
SFC-Tree, source: [Liu 2014]

Recognition: Previous Work

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 - Histogram of Oriented Gradients (HOG) - [Greenhalgh 2012, Zaklouta 2011]
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 - Categories-first-assigned Tree (CTA-Tree) - [Liu 2013]
 - Split-Flow Cascade Tree (SFC-Tree) - [Liu 2014]
- Followed by feature classifiers
 - Random Forest - [Zaklouta 2011]
 - SVM, Hierarchical SVM, Kernel SVM [Greenhalgh 2012]
 - Multi-layer Perceptron (MLP)

Recognition: Previous Work

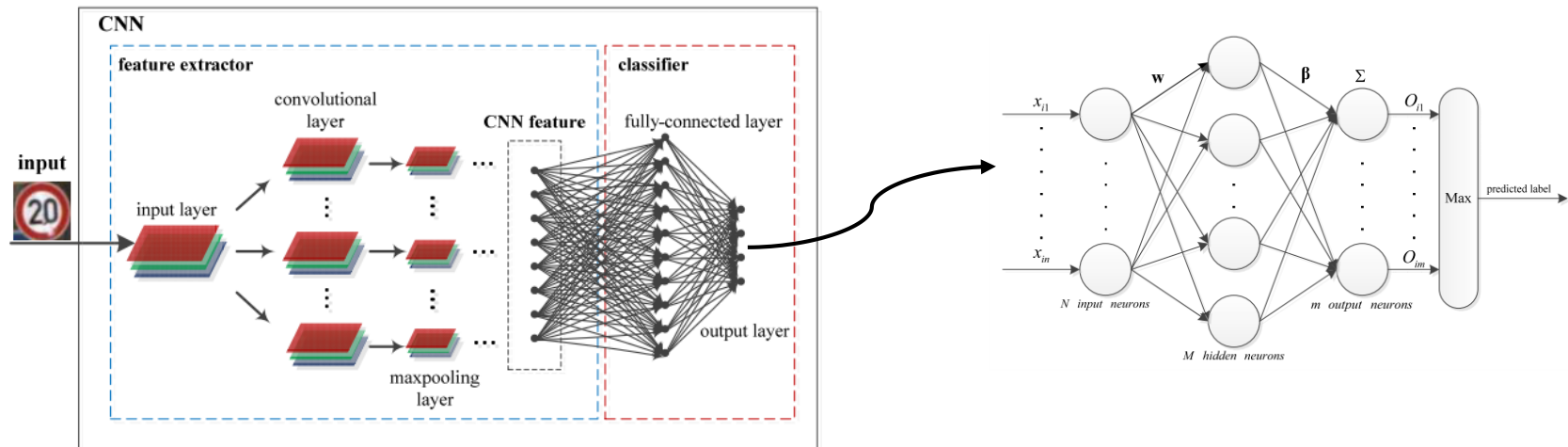
- Deep Learning and ConvNets (CNN)
 - Committee of DNN (Muti-Column DNN) - [Cireşan 2012]



Source: [Cireşan 2012]

Recognition: Previous Work

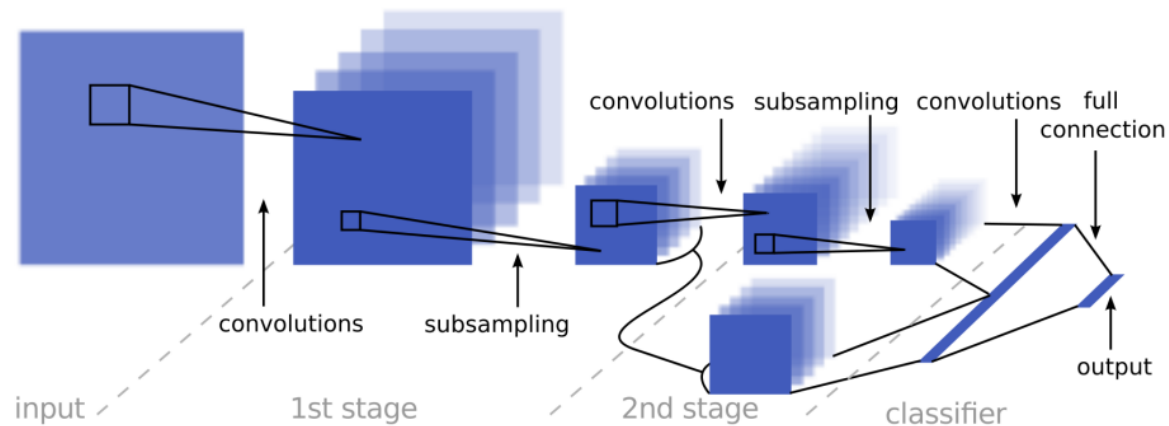
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 - Committee of DNN (Muti-Column DNN) - [Cireşan 2012]
 - Extreme Learning Classifier (ELC) with CNN - [Zeng 2015]



Source: [Zeng 2015]

Recognition: Previous Work

- Deep Learning and ConvNets (CNN)
 - Committee of DNN (Muti-Column DNN) - [Cireşan 2012]
 - Extreme Learning Classifier (ELC) with CNN - [Zeng 2015]
 - Multi-Scale CNN - [Sermanet 2011]



Source: [Sermanet 2011]

Recognition: Limitations

- Handcrafted features
 - Feature engineering comes with a price - [Brkic 2010, Filkovic 2014]

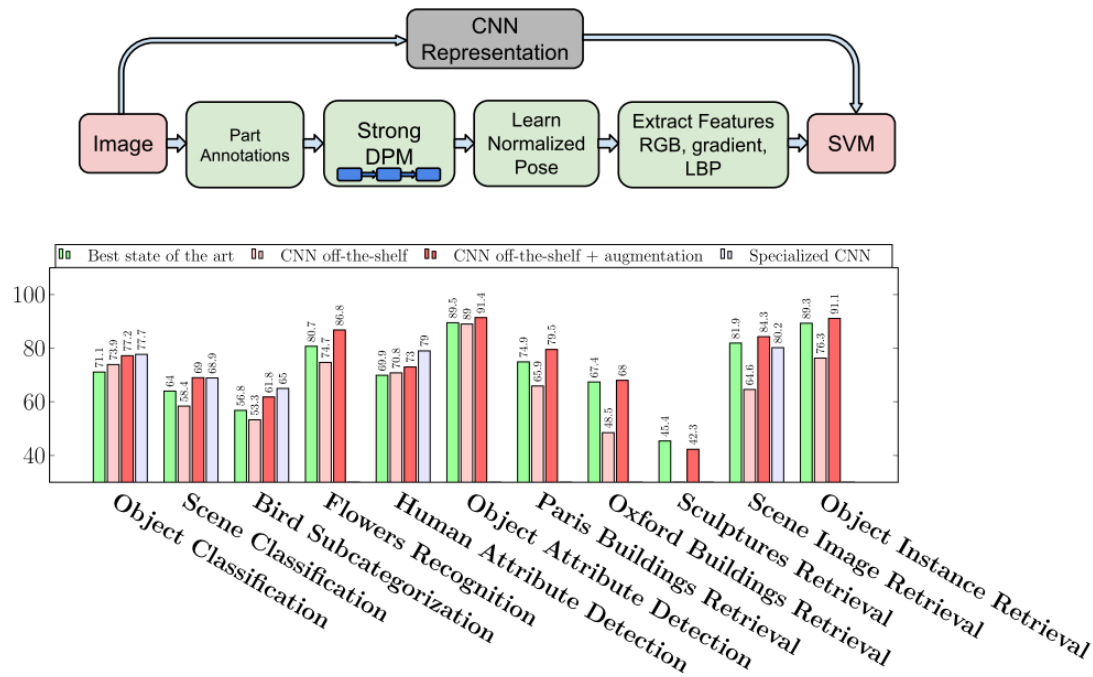


Source: [Brkic 2010]

Recognition: Limitations

- Handcrafted features

- Feature engineering comes with a price - [Brkic 2010, Filkovic 2014]
- Shallow features, less discriminant, struggle with large dataset [Razavian 2014]
- Outperformed by CNN in large-scale problems - [Razavian 2014]



Source: [Razavian 2014]

Recognition: Limitations

- Deep Learning (CNN)
 - Complexity of training for large scale datasets (100+ classes)

Recognition: Limitations

- Deep Learning (CNN)
 - Complexity of training for large scale datasets (100+ classes)
 - German Traffic Sign Recognition Benchmark (GTSRB) – 43 classes



Source: <http://benchmark.ini.rub.de/?section=gtsrb>

Recognition: Limitations

- Deep Learning (CNN)
 - Complexity of training for large scale datasets (100+ classes)
 - German Traffic Sign Recognition Benchmark (GTSRB) – 43 classes
 - Belgium Traffic Sign dataset (BelgiumTS) – 63 classes



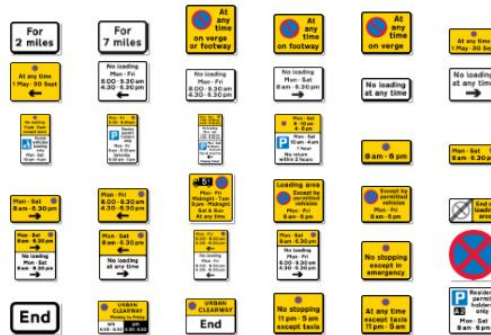
Source: <http://btsd.ethz.ch/shareddata/>

Recognition: Limitations

- Large-scale Dataset (100+ Classes)
 - How far are we from the solution? - [Mathias, 2013]



Road Work



On-street Parking

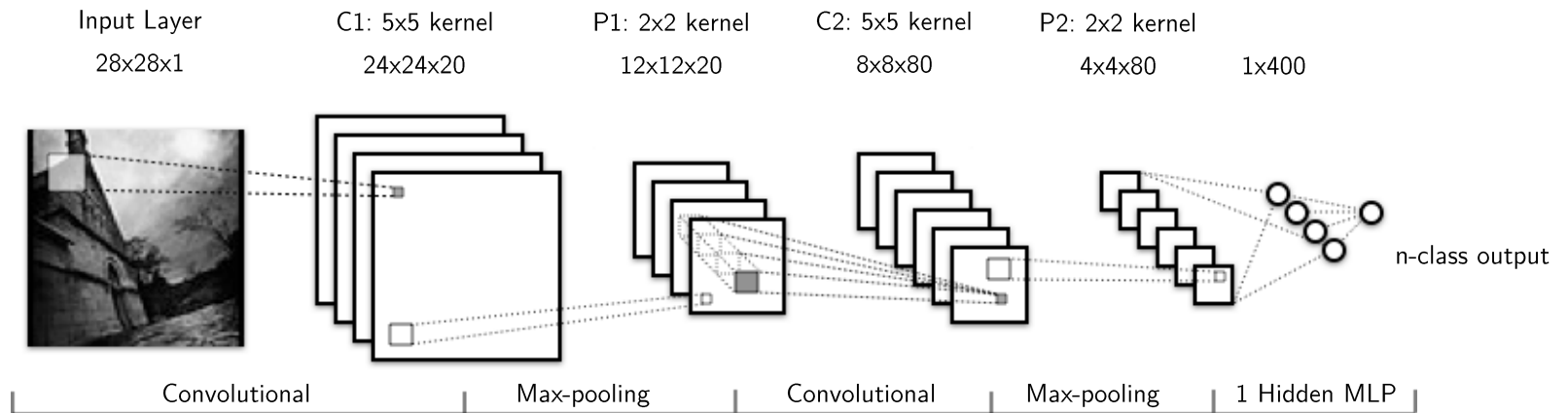


Motorway Signs

Source: <https://www.gov.uk/government/publications/the-highway-code-traffic-signs>

Recognition: Methods

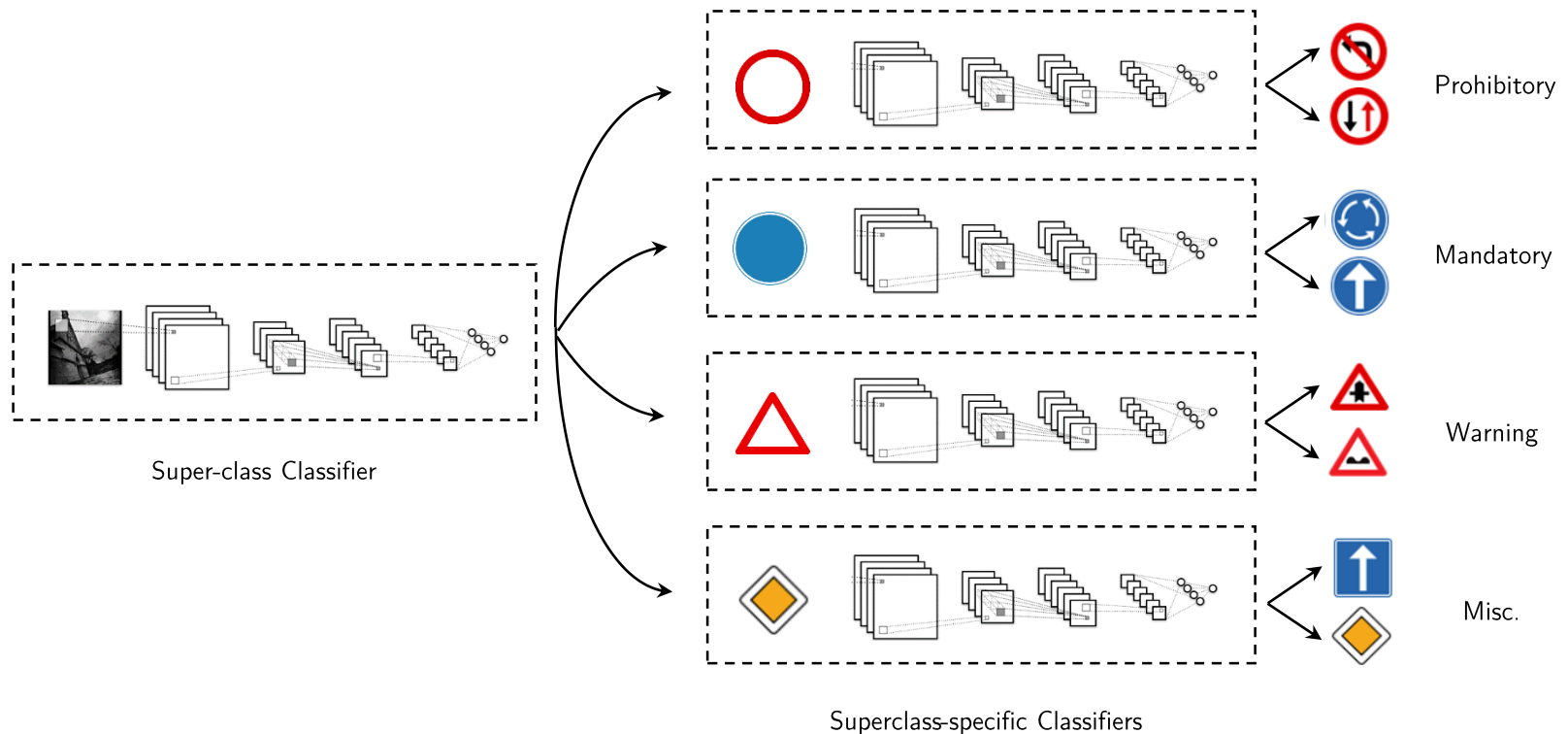
- Hierarchical CNN (H-CNN)
 - Exploit the visual features (shapes)
 - Solution to address large-scale classification



Reproduced from: <http://deeplearning.net/tutorial/lenet.html>

Recognition: Methods

- Hierarchical CNN (H-CNN)
 - Exploit the visual features (shapes)
 - Solution to address large-scale classification



Recognition: Methods

- Super-class hypothesis
 - Will the super-class network develop a shape-based filters (i.e. feature maps)?
 - Will these filters be extensible to non-represented classes?



GTSRB Dataset



BelgiumTS Dataset







Recognition: Results

- GTSRB Competition

Method	Accuracy
2-stage HOG+SVM [Yang 2014]	99.52%
Committee of CNNs [Ciresan 2012]	99.46%
Benchmark – Human Performance	98.84%
Multi-Scale CNNs [Sermanet 2011]	98.31%
Random Forests [Zaklouta 2011]	96.14%
Our Method – Hierarchical CNN	94.98%

Recognition: Results

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Recognition: Results

- GTSRB Competition

Method	Architecture	Parameters	Input
Committee of CNNs [Ciresan 2012]	3 Conv [20, 40, 800] – 2 Hidden Layers * 8 CNN	40e6	48x48
Multi-Scale CNNs [Sermanet 2011]	2 Conv [104, 8640] – 2 Hidden Layers	5e6	32x32
Hierarchical CNN [Our Method]	2 Conv [20, 80] – 1 Hidden Layer [400]	0.75e6	28x28

Detection

Detection: Previous Work

- Detection Proposals
 - Colour based, probability maps - [Yang 2014]

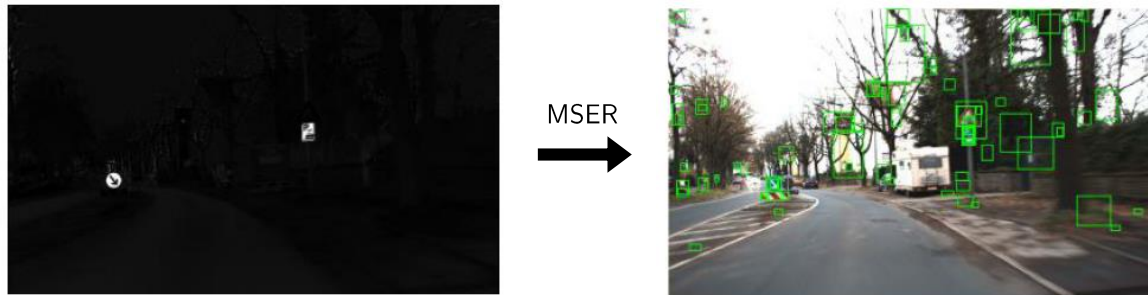


Colour Probability Map (CPM) into red and blue
Image reproduced from [Yang 2012]

Detection: Previous Work

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- Handcrafted Detectors
 - Same as classifier feature detectors, HOG, IFC - [Yang 2014]

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- Multi-block Normalized Locale Binary Pattern (MN-LBP) - [Liu 2014]

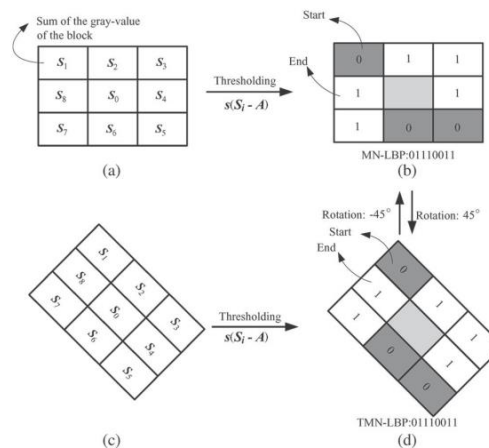
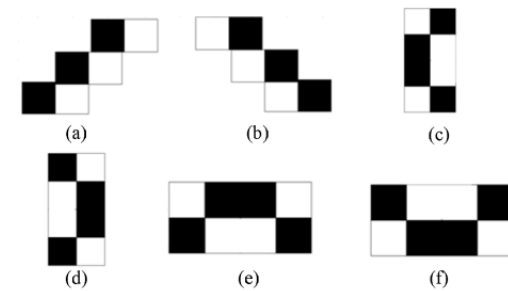
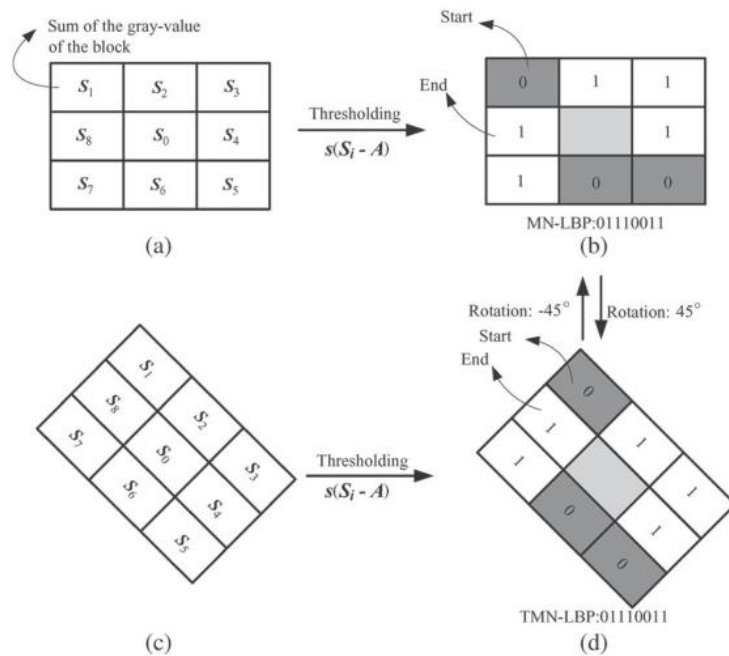


Image source [Liu 2014]

Detection: Previous Work

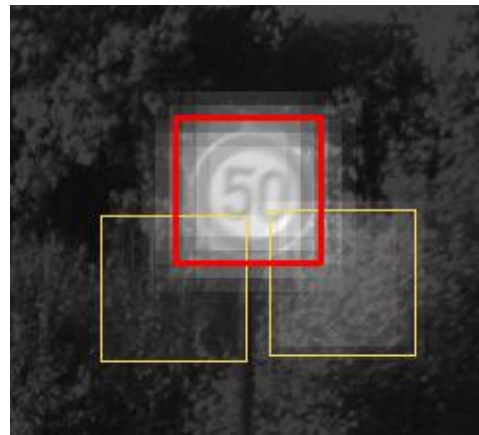


Extended Haar-like features
Image source [Liu 2013]

Left: MN-LBP, right: Tilted MN-LBP
Image source [Liu 2014]

Detection: Previous Work

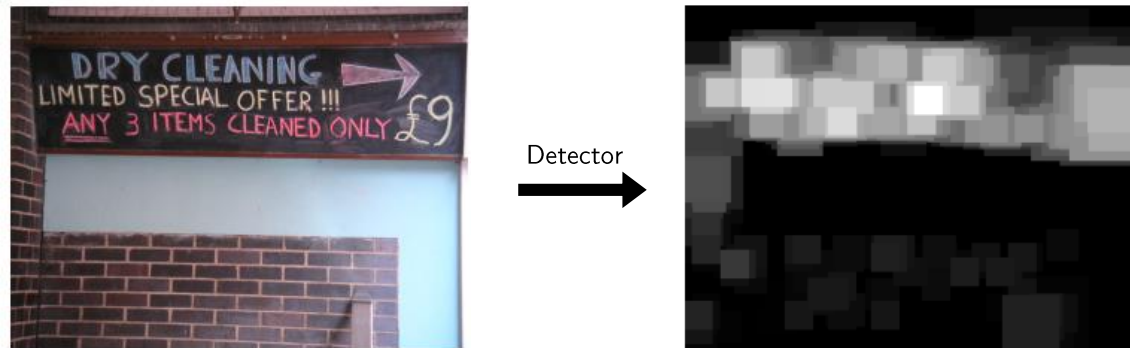
- Detection Proposals
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 - Same as classifier feature detectors, HOG, IFC - [Yang 2014]
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- Suppression
 - Non-Maximum Suppression



Detection: Previous Work

- Deep Learning Detectors

- CNN classifier, sliding window at different scales - [Kobchaisawat 2014, Wang 2012, Coates 2011]



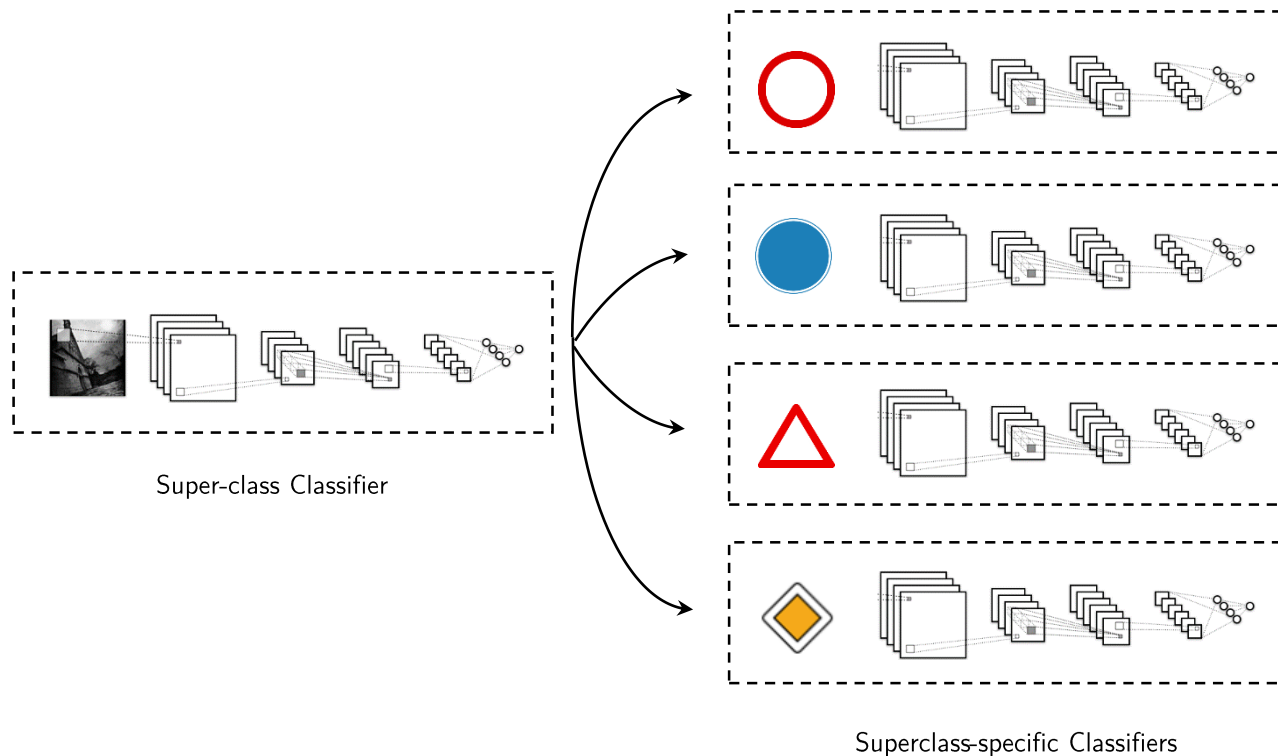
Confidence map of the detector
Reporduced from: [Coates 2014]

Detection: Previous Work

- Deep Learning Detectors
 - CNN classifier, sliding window at different scales - [Kobchaisawat 2014, Wang 2012, Coates 2011]
 - Overfeat: CNN classifier with region detector (regressor) - [Sermanet 2013]

Detection: Methods

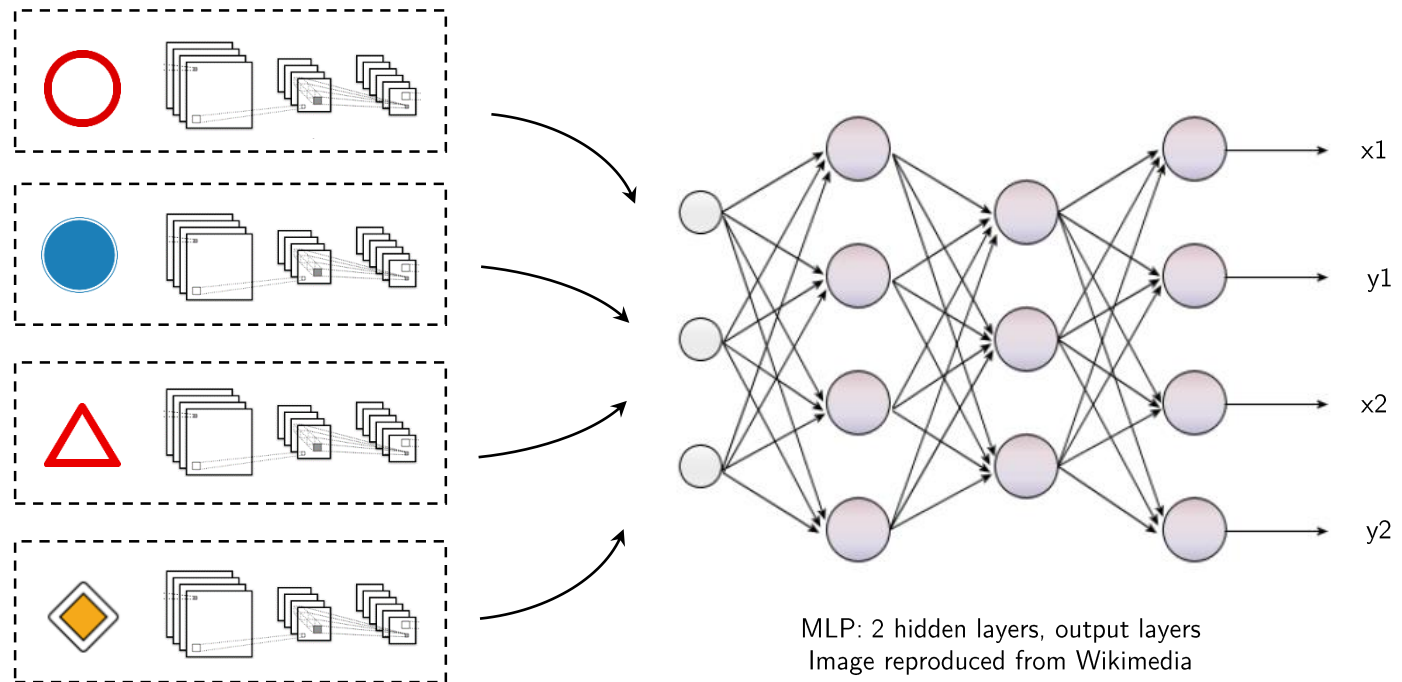
- Superclass-specific Detector
 - Use convolutional features learned from the classifier
 - Train MLP to predict location of traffic sign within the window



Detection: Methods

- Superclass-specific Detector

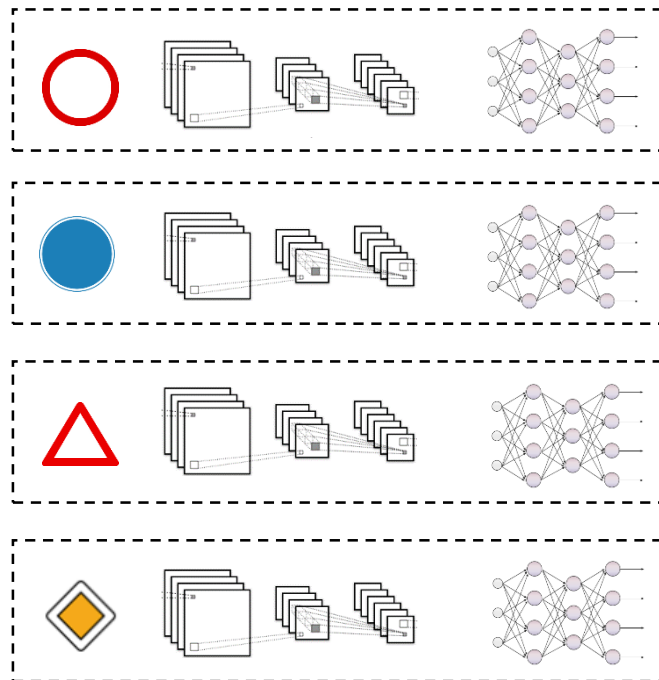
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Superclass-specific Classifiers

Detection: Methods

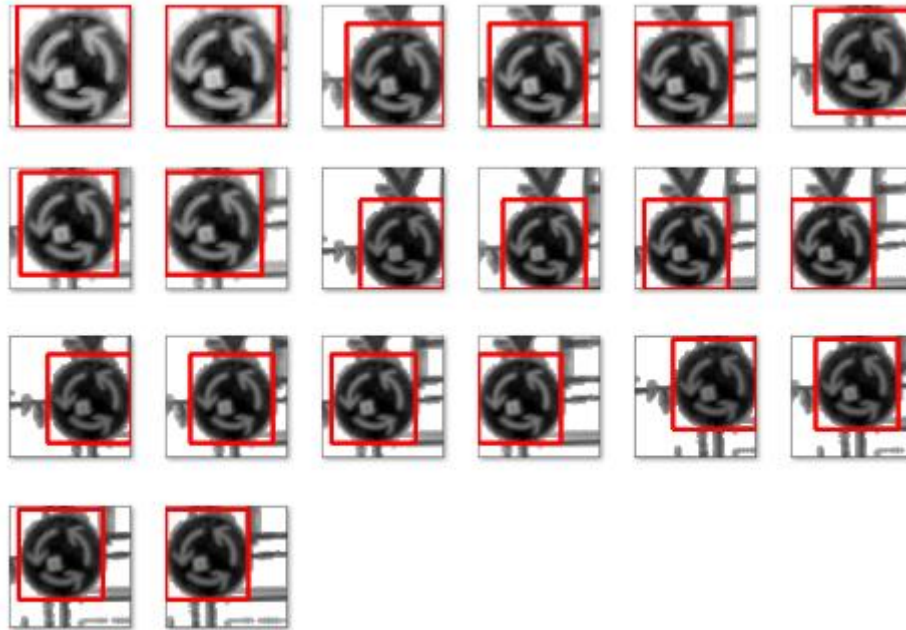
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Superclass-specific Detectors

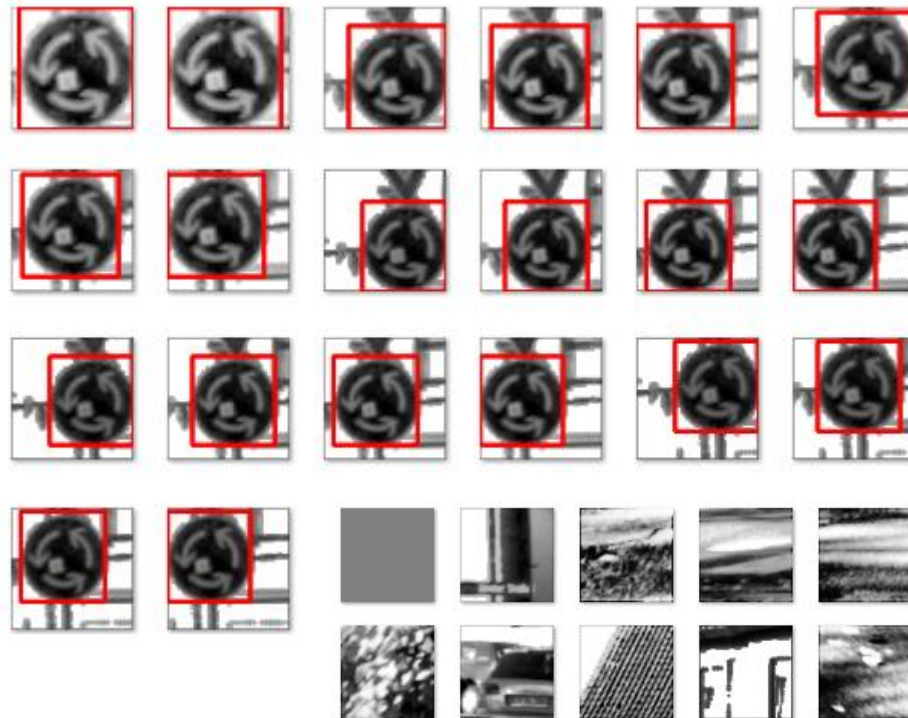
Detection: Methods

- Superclass-specific Detector
 - Sample true positives at different positions/scales within the window



Detection: Methods

- Superclass-specific Detector
 - Sample true positives at different positions/scales within the window
 - Sample true negatives from the natural image background

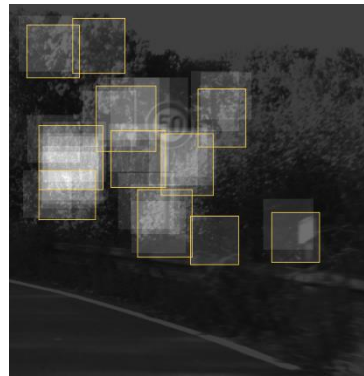


Detection: Methods

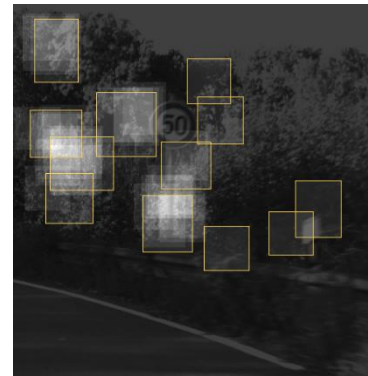
- Experiments
 - Sampling only true positives



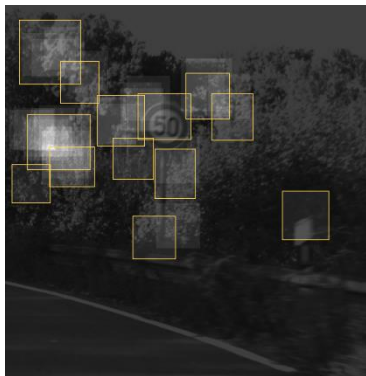
1



2



3



4



5



6

Detection: Methods

- Experiments
 - Huge search space (natural images)



Detection: Results

- Currently, only circle-shaped super-classes
 - Prohibitory, Mandatory

Conclusion

- Recognition
 - CNN has potential to address large-scale datasets (100+ classes)
 - Scalable/extensible to un-seen unseen classes during training
- Detection
 - If well-trained, overcome the problem of hand-crafted
 - With more effort, possible potential to reach state-of-the art performance
- Tracking
 - Enabling the real-time system to locate the position of the traffic sign on the map
- Trade-off
 - GTSRB and GTSDb competitions favour accuracy and complexity
 - Real-time systems favour simplicity and speed

References

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Thank you

Questions